

# DASH: Modelling and Analysis of Declarative State-Based Transition Systems

Work in Progress (\*)

Jose Serna, **Nancy A. Day**, and Shahram Esmaeilsabzali  
With past contributions by Sabria Farheen

Waterloo Formal Methods Lab  
David R. Cheriton School of Computer Science  
University of Waterloo

Future of Alloy Workshop  
Apr 2018

<http://129.97.7.33:8080/dash/>

(\*) In International Workshop on Model-Driven Requirements Engineering (MoDRE) © IEEE International Requirements Engineering (RE), Sep 2017

# Modelling Transition Systems of Reactive Systems

- ▶ Modelling the control-oriented aspects of a system can be done naturally in **hierarchical and concurrent control states** (*i.e.*, the Statecharts family of languages).
  - ▶ Control states means a state with a name.
- ▶ Control-oriented modelling languages lack abstractions for modelling data.
- ▶ We need both! An **integrated** model that describes both **control** and **data** aspects of the system at an abstract level.
- ▶ **Goal:** a natural extension to Alloy to create these integrated models.

# Modelling Transition Systems

- ▶ A transition system (TS) has: **snapshots** (variables with values) and **transitions**.

# Modelling Transition Systems

- ▶ A transition system (TS) has: **snapshots** (variables with values) and **transitions**.
- ▶ Control states are a means of **sequencing transitions** by **factoring/grouping** snapshots that share the same set of possible future behaviours.
- ▶ Typically, the names of control states are **user-observable** elements of the model (*i.e.*, red, yellow, green of a traffic light) so are natural for modellers.

# Modelling Transition Systems

- ▶ A transition system (TS) has: **snapshots** (variables with values) and **transitions**.
- ▶ Control states are a means of **sequencing transitions** by **factoring/grouping** snapshots that share the same set of possible future behaviours.
- ▶ Typically, the names of control states are **user-observable** elements of the model (*i.e.*, red, yellow, green of a traffic light) so are natural for modellers.
- ▶ **Hierarchical** states provide more model decomposition and a natural way to express priority.
- ▶ **Concurrent** states provide a separation of concerns for aspects of the model that can happen at the “same” time.

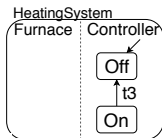
# Modelling Transition Systems

- ▶ A transition system (TS) has: **snapshots** (variables with values) and **transitions**.
- ▶ Control states are a means of **sequencing transitions** by **factoring/grouping** snapshots that share the same set of possible future behaviours.
- ▶ Typically, the names of control states are **user-observable** elements of the model (*i.e.*, red, yellow, green of a traffic light) so are natural for modellers.
- ▶ **Hierarchical** states provide more model decomposition and a natural way to express priority.
- ▶ **Concurrent** states provide a separation of concerns for aspects of the model that can happen at the “same” time.
- ▶ **Events** are occurrences of user actions; or internal actions to model cascading effects between concurrent regions.

```

1  abstract sig ValvePos {} ← Alloy
2  one sig OpenPos, ClosedPos extends ValvePos {}
3  abstract sig Room {}
4
5  state HeatingSystem { ← control state
6      valve: Room -> ValvePos ← snapshot variables
7      desiredTemp: Room -> Int
8      ...
9      event deactivate {} ← create an event
10     init { ← initial snapshot constraint
11         all r: Room | r.valve = ClosedPos ← Alloy
12     }
13     conc state Furnace { ... }
14     conc state Controller {
15         default state Off { }
16         state On { ← control state
17             trans t3 { ← transition
18                 on heatSwitchOff ← event
19                 goto Off
20                 do r.valve' = ClosedPos ← Alloy (w/ prime)
21                 send deactivate ← send an event
22             }
23         ...
24     }
25     ...
26 }

```



# Syntax of Core Dash

Everything in Alloy plus:

```
1  [conc|default] state <name> { ... }
2
3  trans <name> {
4      from <src_state>
5      on <trigger_event>  <----- on/when = precondition
6      when <alloy>
7      goto <dest_state>
8      do <alloy>  <----- postcondition
9      send <generated_event>
10 }
11
12 event <name> {}
13
14 condition <name> {}
```



# Dash Features

- ▶ Transitions understood within context (source state, *etc.*)
  - ▶ Concise
  - ▶ Permits factoring by state, event, and condition
  - ▶ If no natural control states, trans are loops on enclosing state

# Dash Features

- ▶ Transitions understood within context (source state, *etc.*)
  - ▶ Concise
  - ▶ Permits factoring by state, event, and condition
  - ▶ If no natural control states, trans are loops on enclosing state
- ▶ Global access to variables, but namespaces by state

# Dash Features

- ▶ Transitions understood within context (source state, etc.)
  - ▶ Concise
  - ▶ Permits factoring by state, event, and condition
  - ▶ If no natural control states, trans are loops on enclosing state
- ▶ Global access to variables, but namespaces by state
- ▶ Transition comprehension (patterns)

```
trans to_idle {  
  from * on hang_up goto idle  
}
```

# Dash Features

- ▶ Transitions understood within context (source state, etc.)
  - ▶ Concise
  - ▶ Permits factoring by state, event, and condition
  - ▶ If no natural control states, trans are loops on enclosing state
- ▶ Global access to variables, but namespaces by state
- ▶ Transition comprehension (patterns)

```
trans to_idle {  
  from * on hang_up goto idle  
}
```

- ▶ Add-ons:

```
addon (do incErrorCounter)  
  to (from * goto Error)  
addon (do incErrorCounter) to t19
```

# Dash Features

- ▶ Transitions understood within context (source state, etc.)
  - ▶ Concise
  - ▶ Permits factoring by state, event, and condition
  - ▶ If no natural control states, trans are loops on enclosing state
- ▶ Global access to variables, but namespaces by state
- ▶ Transition comprehension (patterns)

```
trans to_idle {  
  from * on hang_up goto idle  
}
```

- ▶ Add-ons:

```
addon (do incErrorCounter)  
  to (from * goto Error)  
addon (do incErrorCounter) to t19
```

- ▶ Transition templates (reusable)

# Semantics of Dash

- ▶ A “big” step (model’s response to env) can be multiple transitions in different concurrent states.
- ▶ **Philosophy for Semantic Decisions:** Atomicity of transitions; internal sequencing of transitions in concurrent states should be rare.

# Semantics of Dash

- ▶ A “big” step (model’s response to env) can be multiple transitions in different concurrent states.
- ▶ **Philosophy for Semantic Decisions:** Atomicity of transitions; internal sequencing of transitions in concurrent states should be rare.
- ▶ Using the framework of Esmaeilsabzali:
  - ▶ **Concurrency:** only one concurrent state can take a transition in a big step (avoids race conditions and makes model’s behaviour more understandable).
  - ▶ **Big-step Maximality:** only one transition per concurrent region in a big step (avoids potentially infinite big-steps).
  - ▶ **Event Lifeline:** events last the entire big step.
  - ▶ **Variable Lifeline:** variables change their values in small steps.
  - ▶ **Priority:** Outer state over inner state.

# Semantics: Frame Problem

- ▶ Mismatch:
  - ▶ In control-oriented modelling languages, any unchanged variable keeps its value in the next state (like a program).
  - ▶ In declarative modelling languages, a variable must be explicitly constrained.



# Semantics: Frame Problem

- ▶ Mismatch:
  - ▶ In control-oriented modelling languages, any unchanged variable keeps its value in the next state (like a program).
  - ▶ In declarative modelling languages, a variable must be explicitly constrained.
- ▶ Our solution:
  - ▶ If variable  $a$  is NOT designated environmental and is not mentioned in the action of the taken transition, it keeps its value from the previous snapshot.
  - ▶ To override this semantics, action can be that variable  $a$  must be within its range of values ( $0 \leq a' \leq 100$ ).

## Tool Chain: xText

- ▶ Grammar for Dash (which includes Alloy)
- ▶ “Smart” editor automatically created
- ▶ Transformation rules to:
  1. Transform to Core Dash (state hierarchy plus fully detailed transitions)
  2. Transform Core Dash to Alloy
    - ▶ Transition names are present in Alloy so it's easier to relate a counterexample to the model.

# Analyzing Transition Systems in Alloy

BMC (Bounded Model Checking)

Scoped TCMC (Transitive-Closure-based Model Checking for CTLFC)

Significance axioms to ensure the TS is “big enough”

Table: Deducing Complete Model Checking Results

Property		Scoped TCMC		BMC using ordering	
		Pass	Fail	Pass	Fail
Safety		Ambiguous	Real Bug	Ambiguous	Real Bug
Finite Liveness	w/o dead-loop	Ambiguous	Real Bug	Real Pass	Ambiguous
	w/ dead-loop	Real Pass	Ambiguous		
Infinite Liveness		Ambiguous	Real Bug	<i>Cannot Express</i>	
Existential		Real Pass	Ambiguous	<i>Cannot Express</i>	

# Summary

- ▶ **Dash** is an extension of Alloy to create an **integrated** model that describes both **control** and **data** aspects of the system at an abstract level.
- ▶ Dash provides explicit syntax for:
  - ▶ **Transitions**, preconditions, postconditions
  - ▶ Hierarchical and concurrent **control states**
  - ▶ **Events** to allow cascading effect between concurrent regions
  - ▶ Semantics chosen to match **combination of declarative and control-oriented** modelling paradigms and address the frame problem.
  - ▶ Syntactic sugar for conciseness (transition comprehension, add-ons, factoring by events, conditions, transition templates).
- ▶ Dash is fully integrated with Alloy for everything else (expressions, data abstractions, functions, and predicates).